CLAIMS

What is claimed is:

- 1 1. A method of texture filtering, comprising the steps of:
- 2 receiving input information relating to polygon and texture data; and
- morphing a texture reconstruction filter characteristic based upon the input
- 4 information so that after subsamples are aggregated, an effective filter characteristic
- 5 matches the texture reconstruction filter characteristic of a texture reconstruction filter
- 6 used for coarse sampling.
- 1 2. The method of claim 1 wherein the input information relates to a rate of
- 2 sampling of the polygon data.
- 1 3. The method of claim 1 wherein the input information relates to a degree of
- 2 warping per texture coordinate.
- 1 4. The method of claim 1 wherein the effective filter characteristic matches the
- 2 characteristic of a bilinear filter.
- 1 5. The method of claim 1 wherein the effective filter characteristic matches the
- 2 characteristic of a combination of a bilinear filter and a box filter.
- 1 6. The method of claim 1 wherein the effective filter characteristic matches the
- 2 characteristic of a combination of a linear filter between MIP levels and a combination
- 3 of a bilinear filter and a box filter.
- The method of claim 1 wherein the morphing of the texture reconstruction filter
- 2 characteristic is performed in a continuous manner.
- 1 8. The method of claim 1 wherein the morphing of the texture reconstruction filter
- characteristic is determined by a value $\beta = \min(\delta * (n-1)/n, 1.0)$ wherein δ is a degree of
- 3 warping per texture coordinate and n is a sampling rate of the polygon data.

- 1 9. An electronically-readable medium having embodied thereon a program, the
- 2 program being executable by a machine to perform method steps for texture filtering,
- 3 the method steps comprising:
- 4 receiving input information relating to polygon data and texture data; and
- 5 morphing a texture reconstruction filter characteristic based upon the input
- 6 information so that after subsamples are aggregated, an effective filter characteristic
- 7 matches the texture reconstruction filter characteristic of a texture reconstruction filter
- 8 used for coarse sampling.
- 1 10. The electronically-readable medium of claim 9 wherein the input information
- 2 relates to a rate of sampling of the polygon data.
- 1 11. The electronically-readable medium of claim 9 wherein the input information
- 2 relates to a degree of warping per texture coordinate.
- 1 12. The electronically-readable medium of claim 9 wherein the morphing of the
- 2 texture reconstruction filter characteristic is performed in a continuous manner.
- 1 13. An apparatus for texture filtering, comprising:
- a first module adapted to detect a sampling rate n of polygon data;
- a second module coupled to the first module adapted to select a filtering mode
- based upon a sampling rate n of polygon data and a degree of warping δ per texture
- 5 coordinate; and
- a third module coupled to the second module adapted to compute texel blending
- 7 factors based on the filtering mode determined by the second module.
- 1 14. The apparatus of claim 13 wherein the second module selects a filtering mode
- 2 based upon a value β = min (δ * (n-1)/n, 1.0).
- 1 15. The apparatus of claim 13 further comprising a fourth module coupled to the
- third module adapted to detect a degree of warping δ per texture coordinate.

6

7

1	16.	An apparatus for texture filtering comprising:
2		a filter select module adapted to select a filtering mode based upon a sampling
3	rate n of polygon data; and	
4		a texel blending module coupled to the filter select module adapted to compute
,5	texel blending factors based on the filtering mode determined by the filter select	
6	module.	
1	17.	The apparatus of claim 16 wherein the filter select module determines a filter
2	characteristic of a selected filtering module based upon the sampling rate n and a	
3	degree of warping δ per texture coordinate.	
1		
1	18.	The apparatus of claim 16 wherein the filter select module selects the filtering
2	mode based upon a value $\beta = \min (\delta * (n-1)/n, 1.0)$.	
1	19.	An apparatus for texture filtering, comprising:
2		means for receiving input information relating to polygon data and texture data;
3	and	
4		means for morphing a texture reconstruction filter characteristic based upon the
5	input information so that after subsamples are aggregated, an effective filter	

characteristic matches the texture reconstruction filter characteristic of a texture

reconstruction filter used for coarse sampling.